# ICON FUV

#  stray light

# ICN-FUV-081

## REV - B

# 2015-september-17

As Run on: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Date/Time

By: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Test Conductor

# Document Revision Record

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| --- | --- | --- | --- |
| **Rev.** | **Date** | **Description of Change** | **Approved By** |
| - | July 7, 2015 | Initial Draft Released |  |
|  | September 17, 2015 | Updates after calibration procedure discussion |  |
|  |  |  |  |

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**TBDs**

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| WRITTEN BY Harald Frey DATE 07/JULY/15APPROVALSENG : \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ DATE \_\_\_\_\_\_\_\_\_\_SCI (FUV) : \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ (SM) DATE \_\_\_\_\_\_\_\_\_\_PM (FUV): \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_(CC) DATE \_\_\_\_\_\_\_\_\_\_P/L SE : \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_(SH) DATE \_\_\_\_\_\_\_\_\_\_PSE : \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ (ET) DATE \_\_\_\_\_\_\_\_\_\_QA: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_(JF) DATE \_\_\_\_\_\_\_\_\_\_  | REVISIONS:B – September 17, 2015 |
| 1.0 OBJECTIVE, 2.0 APPLICATION, 3.0 DRAWINGS and DOCUMENTS, 4.0 REQUIRED PERSONNEL, 5.0 EQUIPMENT, 6.0 CONFIGURATION, 7.0 SAFETY, 8.0 PROCEDURES, 9.0 ANOMALIES. APPENDIX A: EMERGENCY SHUTDOWN and BACKOUT STEPS. |

1. Objective.

This procedure provides the steps to obtain the in-field stray light sensitivity of both FUV channels across the detector. This procedure will be used at CSL in Belgium with FUV in the 6.5 m vacuum chamber.

1. Application.

This procedure will be run three times with light input at 120 nm, 180 nm, and in the visible somewhere between 400-700 nm wherever the light source provides the brightest signal.

1. Drawings and Documents.

ICN-SYS-TBD ICON Contamination Control Plan

ICN-SYS-TBD ICON Purge Plan

1. Required Personnel.

The following personnel are required to be involved for this procedure:

1. Chris Scholz or representative, Quality Assurance
2. Ellen Taylor or Stu Harris, Project/Payload Systems Engineer
3. Cathy Chou or representative, FUV Instrument Lead
4. Stephen Mende or representative, FUV Instrument Scientist

Record assigned Test Conductor \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Record attending Test Personnel \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

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Only the Project Manager, Project Systems Engineer, Payload Systems Engineer, Assigned Test Conductor or Quality Assurance has the authority to make changes in this procedure during operation if the need arises. At least one of these individuals will be present during the full duration of operations.

1. Equipment.

Instrument GSE:

FUV GSE Hardware (Note Serial Number):

1. Keysight N6700B Power Supply \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
2. ICP Communications Emulator (CE) \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
3. ITOS Machine, ITOS Version \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
4. Engineering Model ICP (Foxtrot) \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
5. Keithley \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Harnesses (in addition to Flight Instrument Harness):

1. FUVA- J31 FUV Camera A Data (SWC) \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
2. FUVA- J32 FUV Camera A Power \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
3. FUVA- J33 FUV Camera A HV Power Supply \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
4. FUVA- J34 FUV Camera A HV Arming Plug \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
5. FUVB- J31 FUV Camera B Data (LWC) \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
6. FUVB- J32 FUV Camera B Power \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
7. FUVB- J33 FUV Camera B HV Power Supply \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
8. FUVB- J34 FUV Camera B HV Arming Plug \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
9. FUV- J35 FUV Optics Interfaces \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
10. FUV- J36 FUV Turret Electronics \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
11. FUV- J37 FUV Turret Electronics Output \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
12. FUV- J38 FUV Turret Arming Plug \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
13. Configurations.

FUV is fully integrated. UV alignment is finished and all mirrors and grating are staked and in final positions. Communication is EM ICP to ITOS machine for power, commanding, and data readout. Test plugs and equipment are installed:

* FUV SW Camera FULL HV Enabling Plug is installed
* FUV LW Camera FULL HV Enabling Plug is installed
* FUV Door Lift Assembly is installed (if necessary)
* FUV Turret Counterbalance is installed (if necessary)
* FUV Turret Arming Plug is installed
* Turret at 0 degrees with door opened

Figure 1: Schematic of test setup

Note deviations from above configuration: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Test Conductor Sign-Off on deviations: \_\_\_\_\_\_\_\_\_\_

1. Safety Precautions.

The FUV Instrument should be treated as ESD sensitive, and handled per the requirements listed in IVN-SYS-003 Environmental Requirements Document (ERD).

The FUV Instrument is contamination sensitive, and must be handled with appropriate care. At all times, the payload shall be handled per the requirements listed in ICN-SYS-006 ICON Contamination Control Plan.

All moving operations outside of a clean room will take place with the payload covered with anti-static bagging. The payload will be handled only by personnel wearing attire appropriate for a FED-STD-209 Class 100,000 cleanroom, including gloves. If the payload is double bagged, personnel will not need full cleanroom suits. However, gloves and wrist straps will be required.

The FUV Instruments must be under purge at all times. See ICN-SYS-TBD ICON Purge Plan for purge monitoring and safety precautions.

1. Procedures.
	1. Test Configuration
		1. FUV instrument installed in CSL vacuum chamber with door opened
		2. Proper movability of cradle confirmed
		3. Electric connection through feedthrough confirmed
		4. Communication between ICP and FUV confirmed
		5. Verify Proper FUV Test Configuration

  FUV SW Camera FULL HV Enabling Plug is in

  FUV LW Camera FULL HV Enabling Plug is in

* + 1. Verify proper vacuum chamber pressure of <10^-3 Pa
		2. Start UV source
		3. Tune monochromator to 135.6 nm
		4. Characterize incoming beam with CSL photodiode
		5. Verify computer time is correct and note start time

Start time: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

* + 1. Verify cover is open

FUV\_cover: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Required: OPENED

Sign off: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ (TC initials required)

* 1. Record instrument temperatures for the record

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| FUV instrument | Temperature at begin of test | Temperature at end of test | OGSE/MGSE | Temperature at begin of test | Temperature at end of test |
| FUVS\_Temp1 |  |  |  |  |  |
| FUVS\_Temp2 |  |  |  |  |  |
| FUVS\_HV\_Temp |  |  |  |  |  |
| FUVL\_Temp1 |  |  |  |  |  |
| FUVL\_Temp2 |  |  |  |  |  |
| FUVL\_HV\_Temp |  |  |  |  |  |
| FUV\_TUR\_Temp |  |  |  |  |  |
| FUV\_OPT\_Temp |  |  |  |  |  |
| FUV\_IMG\_Temp |  |  |  |  |  |
| FUV\_GRAT\_Temp |  |  |  |  |  |

* 1. Instrument Payload Power On
		1.  Execute Section 8.9 in the FUV CPT (ICN-FUV-068) for ICP power on. Attach As-run paper procedure to the appendix. Note FUV CPT revision below

FUV CPT Revision: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Sign off: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ (TC initials required)

* 1. FUV Camera Power Control
		1.  Execute Section 8.10 of the FUV CPT (ICN-FUV-068) for the Camera Power Control. Add notes to attached As-run paper copy of procedure

FUV CPT Revision: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Sign off: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ (TC initials required)

* 1. FUV High Voltage (HV) On
		1.  Execute Section 8.13 in the FUV CPT (ICN-FUV-068) for FUV High Voltage setup. Attach As-run paper procedure to the appendix. Note FUV CPT Revision used below

FUV CPT Revision: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Sign off: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ (TC initials required)

Verify FUV HV Enabling Plugs are in

Sign-off \_\_\_\_\_\_\_\_\_\_\_ (TC initials required)

* 1. SW and LW in-field stray light sensitivity at turret angle 0 degrees
		1.  Change Monochromator to 120 nm

Monochromator wavelength \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ nm

* + 1.  Characterize incoming beam
		2.  Set up ICP to collect 256x256 pixel images
		3.  Verify that turret is at nominal 0 degrees position
		4.  Verify that cradle is set to normal incidence 0 degrees
		5.  Send command: **IOP\_FUV\_DUMP\_ENG\_IMG**  (enter **TDI ID = 0** for A) to capture and readout image to take an integrated picture of 100 frames of 120 msec exposure time and save through ICP with appropriate header information about time, number of frames, cradle position, wavelength, channel,
		6.  Check if spot is recognizable in the SW channel at approximately the center of the image
		7.  Send command: **IOP\_FUV\_DUMP\_ENG\_IMG**  (enter **TDI ID = 1** for B) to capture and readout image to take an integrated picture of 100 frames of 120 msec exposure time and save through ICP with appropriate header information about time, number of frames, cradle position, wavelength, channel,
		8.  Check if spot is recognizable in the LW channel at approximately the center of the image
		9.  Move cradle to input field positions listed in the table below and repeat steps 8.6.6-8.6.9 for each field position. Note total image counts and if a spot is recognizable at all.

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Angle alpha**  | **Angle beta** | **Total counts SW** | **Spot in SW visible? Y/N** | **Total counts LW** | **Spot in LW visible? Y/N** |
| 0 | 0 |  |  |  |  |
| +8 | 0 |  |  |  |  |
| +8 | +8 |  |  |  |  |
| -8 | +8 |  |  |  |  |
| -8 | 0 |  |  |  |  |
| -8 | -8 |  |  |  |  |
| +8 | -8 |  |  |  |  |
| 0 | 0 |  |  |  |  |

* 1. SW and LW in-field stray light sensitivity at turret angle 0 degrees
		1.  Change Monochromator to 180 nm

Monochromator wavelength \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ nm

* + 1.  Characterize incoming beam
		2.  Set up ICP to collect 256x256 pixel images
		3.  Verify that turret is at nominal 0 degrees position
		4.  Verify that cradle is set to normal incidence 0 degrees
		5.  Send command: **IOP\_FUV\_DUMP\_ENG\_IMG**  (enter **TDI ID = 0** for A) to capture and readout image to take an integrated picture of 100 frames of 120 msec exposure time and save through ICP with appropriate header information about time, number of frames, cradle position, wavelength, channel,
		6.  Check if spot is recognizable in the SW channel at approximately the center of the image
		7.  Send command: **IOP\_FUV\_DUMP\_ENG\_IMG**  (enter **TDI ID = 1** for B) to capture and readout image to take an integrated picture of 100 frames of 120 msec exposure time and save through ICP with appropriate header information about time, number of frames, cradle position, wavelength, channel,
		8.  Check if spot is recognizable in the LW channel at approximately the center of the image
		9.  Move cradle to input field positions listed in the table below and repeat steps 8.7.6-8.7.9 for each field position. Note total image counts and if a spot is recognizable at all.

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Angle alpha**  | **Angle beta** | **Total counts SW** | **Spot in SW visible? Y/N** | **Total counts LW** | **Spot in LW visible? Y/N** |
| 0 | 0 |  |  |  |  |
| +8 | 0 |  |  |  |  |
| +8 | +8 |  |  |  |  |
| -8 | +8 |  |  |  |  |
| -8 | 0 |  |  |  |  |
| -8 | -8 |  |  |  |  |
| +8 | -8 |  |  |  |  |
| 0 | 0 |  |  |  |  |

* 1. SW and LW in-field stray light sensitivity at turret angle 0 degrees
		1.  Change Monochromator to ~400 nm

Monochromator wavelength \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ nm

* + 1.  Characterize incoming beam
		2.  Set up ICP to collect 256x256 pixel images
		3.  Verify that turret is at nominal 0 degrees position
		4.  Verify that cradle is set to normal incidence 0 degrees
		5.  Send command: **IOP\_FUV\_DUMP\_ENG\_IMG**  (enter **TDI ID = 0** for A) to capture and readout image to take an integrated picture of 100 frames of 120 msec exposure time and save through ICP with appropriate header information about time, number of frames, cradle position, wavelength, channel,
		6.  Check if spot is recognizable in the SW channel at approximately the center of the image
		7.  Send command: **IOP\_FUV\_DUMP\_ENG\_IMG**  (enter **TDI ID = 1** for B) to capture and readout image to take an integrated picture of 100 frames of 120 msec exposure time and save through ICP with appropriate header information about time, number of frames, cradle position, wavelength, channel,
		8.  Check if spot is recognizable in the LW channel at approximately the center of the image
		9.  Move cradle to input field positions listed in the table below and repeat steps 8.8.6-8.8.9 for each field position. Note total image counts and if a spot is recognizable at all.

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Angle alpha**  | **Angle beta** | **Total counts SW** | **Spot in SW visible? Y/N** | **Total counts LW** | **Spot in LW visible? Y/N** |
| 0 | 0 |  |  |  |  |
| +8 | 0 |  |  |  |  |
| +8 | +8 |  |  |  |  |
| -8 | +8 |  |  |  |  |
| -8 | 0 |  |  |  |  |
| -8 | -8 |  |  |  |  |
| +8 | -8 |  |  |  |  |
| 0 | 0 |  |  |  |  |

* 1. SW in-field stray light sensitivity at turret angle -30 degrees (LW will not be used)
		1.  Change Monochromator to 120 nm

Monochromator wavelength \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ nm

* + 1.  Characterize incoming beam
		2.  Set up ICP to collect 256x256 pixel images
		3.  Move turret to -30 degrees position
		4.  Move cradle to compensate for turret angle
		5.  Send command: **IOP\_FUV\_DUMP\_ENG\_IMG**  (enter **TDI ID = 0** for A) to capture and readout image to take an integrated picture of 100 frames of 120 msec exposure time and save through ICP with appropriate header information about time, number of frames, cradle position, wavelength, channel,
		6.  Check if spot is recognizable in the SW channel at approximately the center of the image
		7.  Move cradle to input field positions listed in the table below and repeat steps 8.9.6-8.9.7 for each field position. Note total image counts and if a spot is recognizable at all.

|  |  |  |  |
| --- | --- | --- | --- |
| **Angle alpha**  | **Angle beta** | **Total counts SW** | **Spot in SW visible? Y/N** |
| 0 | 0 |  |  |
| +8 | 0 |  |  |
| +8 | +8 |  |  |
| -8 | +8 |  |  |
| -8 | 0 |  |  |
| -8 | -8 |  |  |
| +8 | -8 |  |  |
| 0 | 0 |  |  |

* 1. SW in-field stray light turret angle -30 degrees (LW will not be used)
		1.  Verify Monochromator is set to 180 nm

Monochromator wavelength \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ nm

* + 1.  Characterize incoming beam
		2.  Set up ICP to collect 256x256 pixel images
		3.  Move turret to -30 degrees position
		4.  Move cradle to compensate for turret angle
		5.  Send command: **IOP\_FUV\_DUMP\_ENG\_IMG**  (enter **TDI ID = 0** for A) to capture and readout image to take an integrated picture of 100 frames of 120 msec exposure time and save through ICP with appropriate header information about time, number of frames, cradle position, wavelength, channel,
		6.  Check if spot is recognizable in the SW channel at approximately the center of the image
		7.  Move cradle to input field positions listed in the table below and repeat steps 8.10.6-8.10.7 for each field position. Note total image counts and if a spot is recognizable at all.

|  |  |  |  |
| --- | --- | --- | --- |
| **Angle alpha**  | **Angle beta** | **Total counts SW** | **Spot in SW visible? Y/N** |
| 0 | 0 |  |  |
| +8 | 0 |  |  |
| +8 | +8 |  |  |
| -8 | +8 |  |  |
| -8 | 0 |  |  |
| -8 | -8 |  |  |
| +8 | -8 |  |  |
| 0 | 0 |  |  |

* 1. SW in-field stray light turret angle -30 degrees (LW will not be used)
		1.  Verify Monochromator is set to ~400 nm

Monochromator wavelength \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ nm

* + 1.  Characterize incoming beam
		2.  Set up ICP to collect 256x256 pixel images
		3.  Move turret to -30 degrees position
		4.  Move cradle to compensate for turret angle
		5.  Send command: **IOP\_FUV\_DUMP\_ENG\_IMG**  (enter **TDI ID = 0** for A) to capture and readout image to take an integrated picture of 100 frames of 120 msec exposure time and save through ICP with appropriate header information about time, number of frames, cradle position, wavelength, channel,
		6.  Check if spot is recognizable in the SW channel at approximately the center of the image
		7.  Move cradle to input field positions listed in the table below and repeat steps 8.11.6-8.11.7 for each field position. Note total image counts and if a spot is recognizable at all.

|  |  |  |  |
| --- | --- | --- | --- |
| **Angle alpha**  | **Angle beta** | **Total counts SW** | **Spot in SW visible? Y/N** |
| 0 | 0 |  |  |
| +8 | 0 |  |  |
| +8 | +8 |  |  |
| -8 | +8 |  |  |
| -8 | 0 |  |  |
| -8 | -8 |  |  |
| +8 | -8 |  |  |
| 0 | 0 |  |  |

* 1. SW in-field stray light sensitivity at turret angle +30 degrees (LW will not be used)
		1.  Change Monochromator to 120 nm

Monochromator wavelength \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ nm

* + 1.  Characterize incoming beam
		2.  Set up ICP to collect 256x256 pixel images
		3.  Move turret to +30 degrees position
		4.  Move cradle to compensate for turret angle
		5.  Send command: **IOP\_FUV\_DUMP\_ENG\_IMG**  (enter **TDI ID = 0** for A) to capture and readout image to take an integrated picture of 100 frames of 120 msec exposure time and save through ICP with appropriate header information about time, number of frames, cradle position, wavelength, channel,
		6.  Check if spot is recognizable in the SW channel at approximately the center of the image
		7.  Move cradle to input field positions listed in the table below and repeat steps 8.8.5-8.8.6 for each field position. Note total image counts and if a spot is recognizable at all.

|  |  |  |  |
| --- | --- | --- | --- |
| **Angle alpha**  | **Angle beta** | **Total counts SW** | **Spot in SW visible? Y/N** |
| 0 | 0 |  |  |
| +8 | 0 |  |  |
| +8 | +8 |  |  |
| -8 | +8 |  |  |
| -8 | 0 |  |  |
| -8 | -8 |  |  |
| +8 | -8 |  |  |
| 0 | 0 |  |  |

* 1. SW in-field stray light sensitivity at turret angle +30 degrees (LW will not be used)
		1.  Change Monochromator to 180 nm

Monochromator wavelength \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ nm

* + 1.  Characterize incoming beam
		2.  Set up ICP to collect 256x256 pixel images
		3.  Move turret to +30 degrees position
		4.  Move cradle to compensate for turret angle
		5.  Send command: **IOP\_FUV\_DUMP\_ENG\_IMG**  (enter **TDI ID = 0** for A) to capture and readout image to take an integrated picture of 100 frames of 120 msec exposure time and save through ICP with appropriate header information about time, number of frames, cradle position, wavelength, channel,
		6.  Check if spot is recognizable in the SW channel at approximately the center of the image
		7.  Move cradle to input field positions listed in the table below and repeat steps 8.8.5-8.8.6 for each field position. Note total image counts and if a spot is recognizable at all.

|  |  |  |  |
| --- | --- | --- | --- |
| **Angle alpha**  | **Angle beta** | **Total counts SW** | **Spot in SW visible? Y/N** |
| 0 | 0 |  |  |
| +8 | 0 |  |  |
| +8 | +8 |  |  |
| -8 | +8 |  |  |
| -8 | 0 |  |  |
| -8 | -8 |  |  |
| +8 | -8 |  |  |
| 0 | 0 |  |  |

* 1. SW in-field stray light sensitivity at turret angle +30 degrees (LW will not be used)
		1.  Change Monochromator to ~400 nm

Monochromator wavelength \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ nm

* + 1.  Characterize incoming beam
		2.  Set up ICP to collect 256x256 pixel images
		3.  Move turret to +30 degrees position
		4.  Move cradle to compensate for turret angle
		5.  Send command: **IOP\_FUV\_DUMP\_ENG\_IMG**  (enter **TDI ID = 0** for A) to capture and readout image to take an integrated picture of 100 frames of 120 msec exposure time and save through ICP with appropriate header information about time, number of frames, cradle position, wavelength, channel,
		6.  Check if spot is recognizable in the SW channel at approximately the center of the image
		7.  Move cradle to input field positions listed in the table below and repeat steps 8.8.5-8.8.6 for each field position. Note total image counts and if a spot is recognizable at all.

|  |  |  |  |
| --- | --- | --- | --- |
| **Angle alpha**  | **Angle beta** | **Total counts SW** | **Spot in SW visible? Y/N** |
| 0 | 0 |  |  |
| +8 | 0 |  |  |
| +8 | +8 |  |  |
| -8 | +8 |  |  |
| -8 | 0 |  |  |
| -8 | -8 |  |  |
| +8 | -8 |  |  |
| 0 | 0 |  |  |

* 1. ITOS power down
		1.  Record time of instrument Power Off \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_
		2.  Start fuv\_off
		3.  Start icp\_off.
		4.  Quit now in prompt
		5.  Foxtrot\_cleanup
1. Anomalies.

Note all anomalies that occurred during procedure:

1. Data Review.

QA Signoff: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ date: \_\_\_\_\_\_\_\_\_\_\_\_\_\_

PSE Signoff: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ date: \_\_\_\_\_\_\_\_\_\_\_\_\_\_APPENDIX A: EMERGENCY SHUTDOWN and BACKOUT STEPS

FIRE:

[1] Stop the operation;

[2] Evacuate the area;

[3] Call 911.

EARTHQUAKE (highly unlikely in Belgium, but better have it in place):

[1] Stop the operation;

[2] Engage brakes on the spacecraft dolly;

[3] Evacuate the area.

VACUUM BREACH:

[1] Stop operations

[2] verify that automatic power off occurred else pull the power plug to FUV