

Signal Strength and Bandwidth for Magnetotelluric Sounding of the Interior of the Moon [#2475]

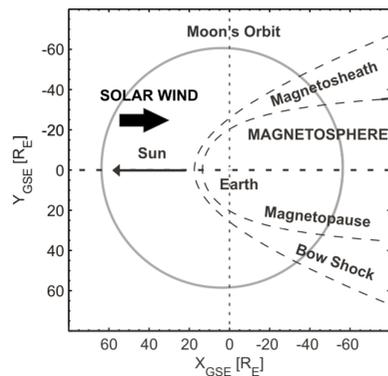
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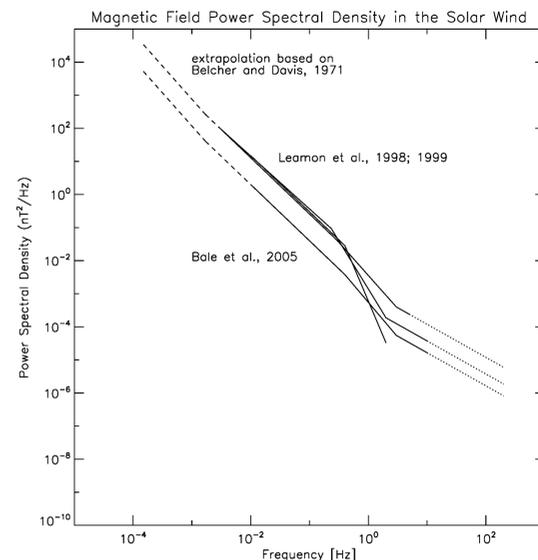
Introduction

- Electromagnetic (EM) sounding is a group of geophysical methods used to characterize the interiors of planetary bodies from 1 m to > 1000 km
 - Previous EM soundings of the Moon performed during the Apollo Era utilized a transfer function method and required both orbiting and surface magnetometers
- In the magnetotelluric (MT) method, the orthogonal components of the horizontal electric and magnetic fields measured on the surface are used to discern the conductivity structure
- The Moon encounters a wide variety of plasma regimes and EM source signals over a broad range of frequencies (above and right)
- Here, we consolidate previous observations to develop a catalog of EM disturbances at the Moon that will be useful for surface MT measurements.



Source Signals

- On the terrestrial planets, electromagnetic discharges (lightning) or magnetic field variations due to interactions with the solar wind can provide MT source signals.
- On airless bodies such as the Moon, solar wind turbulence and other plasma waves can create source signals.



Power spectral density as a function of frequency for magnetic fluctuations in the solar wind (above) and Earth's magnetosphere (below right)

The Moon spends the remaining 1/4 of its orbit in Earth's magnetosphere

Waves in Earth's magnetosphere also provide a robust source of electromagnetic fluctuations from $10^{-4} \text{ Hz} < f < 10^2 \text{ Hz}$

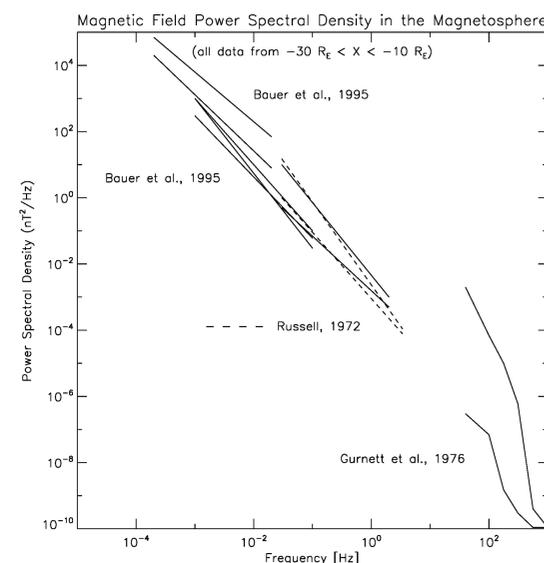
At the highest frequencies, source signal strengths appear slightly lower in the magnetosphere than in the solar wind

Table 1: Target layers, depths, and EM frequency ranges necessary for MT sounding of the Moon:

Target	Depth	Frequency
Crust	0 - 60 km	> 1 Hz
Mantle	60 - 1500 km	10^{-3} - 1 Hz
Core	> 1500 km	$< 10^{-3}$ Hz

The Moon spends 3/4 of its orbit in the solar wind

Observations show that solar wind turbulence can provide a robust source of electromagnetic fluctuations spanning frequencies from $< 10^{-4} \text{ Hz}$ to $> 10^2 \text{ Hz}$



Analysis Methodology

- In MT, assuming a simple planar geometry, the *apparent resistivity* as a function of frequency, ρ_a , is determined from E & B (1), with each wave penetrating the subsurface according to its *skin depth*, δ (2)

$$\rho_a = \frac{1}{5f} \frac{E_y^2 (uV/m)}{B_x^2 (nT)} \text{ ohm-m} \quad (1)$$

$$\delta = \frac{1}{\sqrt{\pi f \mu \sigma}} \sim 500 \sqrt{\frac{\rho}{f}} \text{ m} \quad (2)$$

- Using (1) and (2), inversion procedures convert apparent resistivity, ρ_a , to true resistivity as a function of depth, $\rho(z)$
- This result can be generalized to apply to spherical geometries at longer wavelengths using a response function, $c(\omega)$, as outlined by Weidelt [1972]:

$$c(\omega) = E(r_M, \omega) / i\omega B(r_M, \omega) \rightarrow \rho_a = \omega \mu |c(\omega)|^2$$

Again, the apparent resistivity, ρ_a , can be inverted to find conductivity versus depth

Missions/Instruments

- Electric & magnetic sensors for *Lunette* mission: Neal et al., #2832

